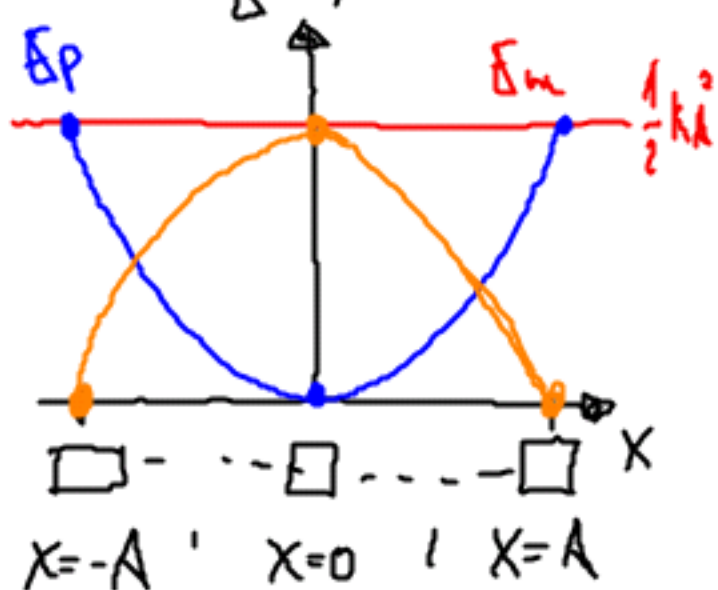


1-

$$x(t) = A \text{sen}(\omega t + \varphi_0)$$

a) M.A.S. es un mov. periódico unidimensional



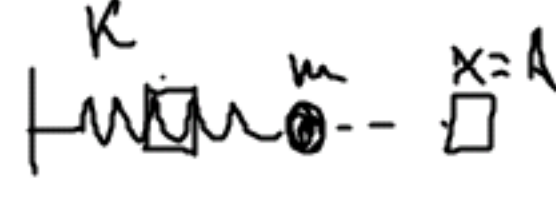
$$E_c = \frac{1}{2} m v^2 = \frac{1}{2} m A^2 \omega^2 \cos^2(\omega t + \varphi_0)$$

$$E_p = \frac{1}{2} K x^2 = \frac{1}{2} K A^2 \text{sen}^2(\omega t + \varphi_0)$$

$$E_m = E_c + E_p = \frac{1}{2} K A^2 [\text{sen}^2(\) + \text{cos}^2(\)]$$

$$E_m = \frac{1}{2} K A^2 = \overline{cte}$$

$E_p = \frac{1}{2} K A^2$	$E_p = 0$	$E_p = \frac{1}{2} K A^2$
$v = 0$	$v_{\text{max}} = A\omega$	$v = 0$
$E_c = 0$	$E_c = \frac{1}{2} K A^2$	$E_c = 0$

b)  $x=A$

$$E_m = \frac{1}{2} k A^2$$



$$E_m' = \frac{1}{2} k A'^2$$

$$\omega = \sqrt{k/m}$$

$$\omega = \omega'$$

$$E_m' = 3 E_m$$

$$\frac{1}{2} k A'^2 = 3 \cdot \frac{1}{2} k A^2$$

$$A' = \sqrt{3} A$$

$$T = \frac{2\pi}{\omega}$$

NO VARIAN

Son indep. de A

$$f = \frac{1}{T} \quad (E_m)$$

$$v = \frac{dx}{dt} = A\omega \cos(\omega t + \varphi_0)$$

$$v_{\max} = A\omega$$

$$v_{\max}' = A'\omega = \sqrt{3} A\omega$$

$$v_{\max} = \sqrt{3} v_{\max}'$$

2-

a)

$$\frac{d\vec{L}}{dt} = \vec{M}$$

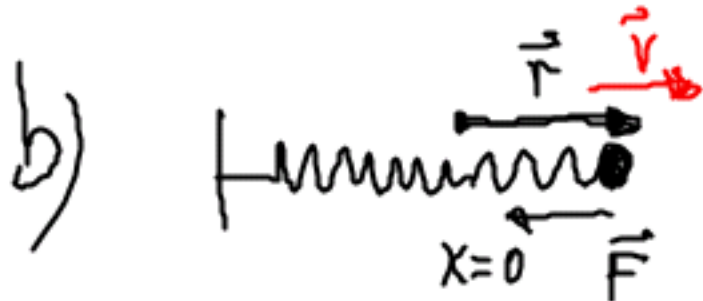
EL CAMBIO INSTANTÁNEO DEL MOM. ANGULAR CN RESPECTO AL TIEMPO ES IGUAL AL MOM. DE LA FUERZA.

$$\vec{L} = \vec{r} \times \vec{p}$$

Demo:

$$\begin{aligned} \frac{d\vec{L}}{dt} &= \frac{d(\vec{r} \times \vec{p})}{dt} = \frac{d\vec{r}}{dt} \times \vec{p} + \vec{r} \times \frac{d\vec{p}}{dt} \\ &= \vec{v} \times \vec{p} + \vec{r} \times \vec{F} = \vec{M} \end{aligned}$$

$\vec{p} = m\vec{v}$
 $\vec{p} \parallel \vec{v}$



$$\vec{M} = \vec{r} \times \vec{F} = \vec{0}$$

$$\vec{r} \parallel \vec{F} \text{ (180°)}$$

$$\boxed{\vec{F} = -k\vec{r}}$$

$$\frac{d\vec{L}}{dt} = \vec{0} \Rightarrow$$

$$\boxed{\vec{L} = cte}$$

$$\vec{L} = \vec{r} \times \vec{p} = \vec{0}$$

$$\vec{r} \parallel \vec{v}$$



i) Giro $\rightarrow L_0 = L_f$

$$I_0 \omega_0 = I_f \omega_f$$

Si DISMINUYE $I \Rightarrow$ AUMENTA ω

$$I = \int r^2 dm \quad (\text{DISMINUYE } r \Rightarrow \text{ENTONCES DISM. } I)$$

ii) No AUMENTA, DISMINUYE

iii) $E_{c_r} = I \omega^2 \Rightarrow \boxed{E_{c_{r_f}} > E_{c_{r_0}}}$

b)

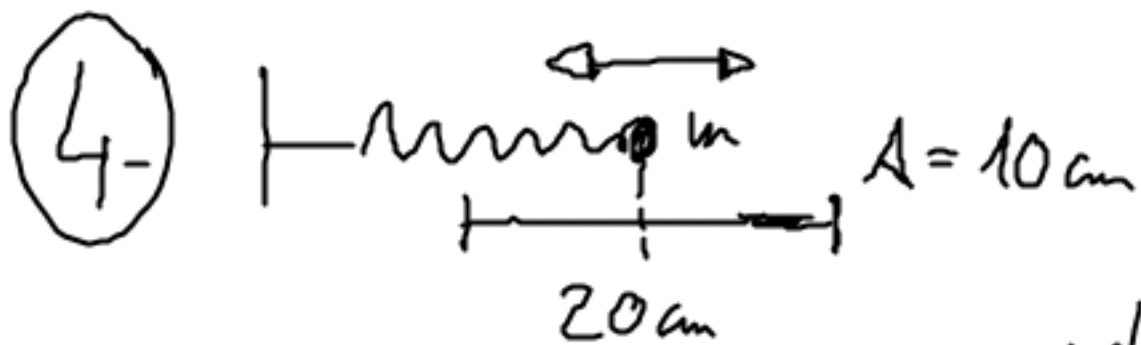
i) (V) , DEFINICIÓN $\Delta E_m = 0$

ii) (F) $W = \int \vec{F} \cdot d\vec{r} = \Delta E_c$

iii) (V) $W = \int_A^B \vec{F} \cdot d\vec{r} = -\Delta E_p$ NO DEPENDE DEL CAMINO



$$W_I = W_{II}$$



a) $T = 5 \text{ s}$

$m = 1 \text{ kg}$

Supongo $\varphi_0 = 0 \text{ rad}$

$$\omega = \frac{2\pi}{T} = \frac{2\pi \text{ rad/s}}{5}$$

$$x(t) = A \sin(\omega t + \varphi_0)$$

$$x(t) = 0,1 \sin\left(\frac{2\pi}{5}t\right) \text{ m}$$

$$v(t) = A\omega \cos(\omega t)$$

$$v(t) = 0,13 \cos\left(\frac{2\pi}{5}t\right) \text{ m/s}$$

$$a(t) = -A\omega^2 \sin(\omega t)$$

$$a(t) = -0,16 \sin\left(\frac{2\pi}{5}t\right) \text{ m/s}^2$$

$$V_{\max} = A\omega = \underline{0,13 \text{ m/s}} \quad \Bigg| \quad a_{\max} = \underline{0,16 \text{ m/s}^2}$$

$(\cos(\frac{2\pi}{5}t) = 1)$ $(\sin(\frac{2\pi}{5}) = -1)$

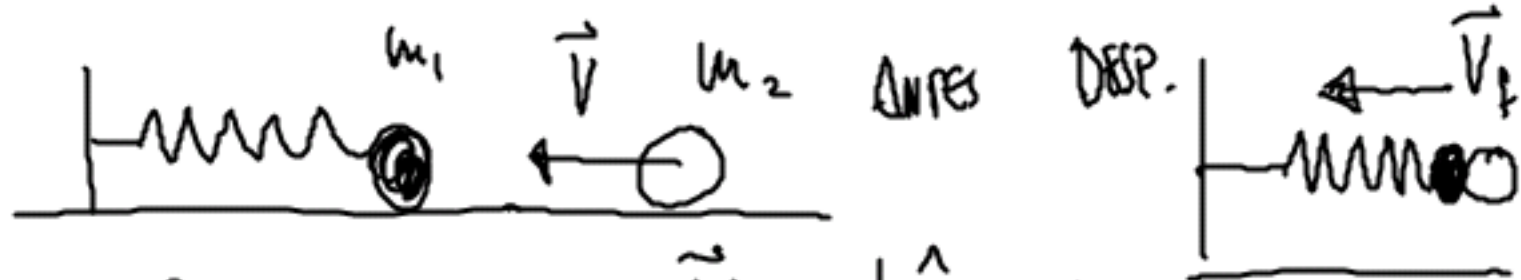
b) $E_c = 3E_p$

$$E_m = E_c + E_p = \frac{1}{2} KA^2$$
$$4E_p = \frac{1}{2} KA^2$$
$$4\left(\frac{1}{2} Kx^2\right) = \frac{1}{2} KA^2$$

$$x = \sqrt{\frac{A^2}{4}} = \pm \frac{A}{2}$$

$$\boxed{x = \pm 5 \text{ cm}}$$

5-



$$m_1 = 200 \text{ g} = 0,2 \text{ kg}$$

$$m_2 = 600 \text{ g} = 0,6 \text{ kg}$$

$$\vec{V} = -4 \hat{i} \text{ m/s}$$

a)

$$\boxed{\vec{P}_0 = \vec{P}_f}$$

\Rightarrow

$$m_2 \vec{V} = (m_1 + m_2) \vec{V}_f$$

$$\boxed{\vec{V}_f = -3 \hat{i} \text{ m/s}}$$

$$\text{CHOQUE} \rightarrow \Delta E_m = E_{c_f} - E_{c_0} = \boxed{-1,2 \text{ J}}$$

b) COMPRESIÓN Máxima (sin pérdidas)

$$\rightarrow E_{cf} = E_{PELAST.}$$

$$\frac{1}{2} (m_1 + m_2) v_f^2 = \frac{1}{2} k x^2$$

$$x = -0,12 \text{ m}$$